

Bayer-Filter Sensor and Beyond

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**Archives of the Future:
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IASA Conference
Mexico, 26–29 September 2022

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United States Patent [19]
Bayer

[11] 3,971,065
[45] July 20, 1976

[54] COLOR IMAGING ARRAY
[75] Inventor: Bryce E. Bayer, Rochester, N.Y.
[73] Assignee: Eastman Kodak Company,
Rochester, N.Y.
[22] Filed: Mar. 5, 1975
[21] Appl. No.: 555,477

[52] U.S. Cl. 358/41; 350/62 SF
350/31; 358/44; 358/46
[51] Int. Cl. H04N 9/24
[58] Field of Search 358/44, 45, 46, 47,
358/48; 350/317, 162 SF; 315/169 TV

[56] References Cited
UNITED STATES PATENTS
2,446,791 8/1948 Schroeder 358/44
2,508,267 5/1950 Kasperowicz 358/44
2,884,483 4/1959 Ehrenhaft et al. 358/44
3,725,572 4/1973 Kurokawa et al. 358/46

Past

11 Claims, 10 Drawing Figures

Summary

- past
- present
- future

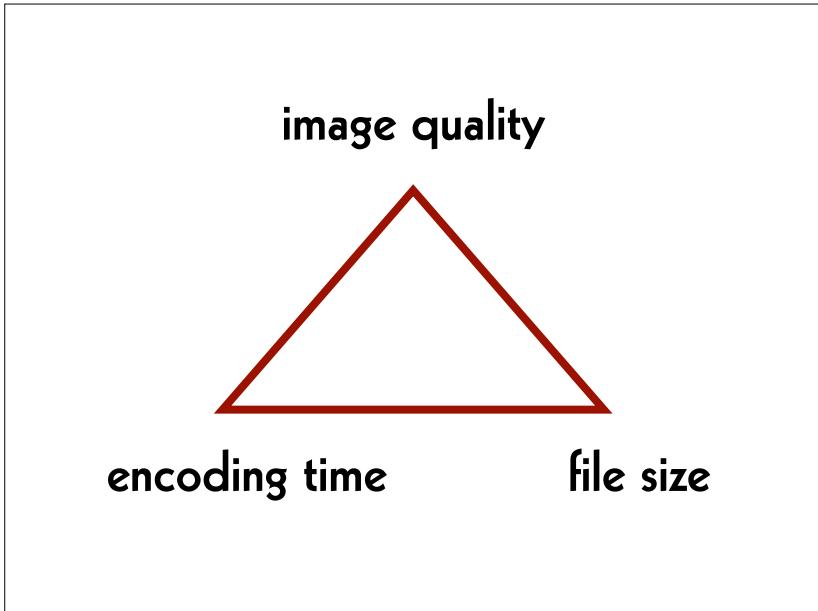
2

Digital Video

- resolution
- bit depth
- linear, power, logarithmic encoding
- colour model
- chroma subsampling and compression
- illuminant

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Bryce E. Bayer (1929–2012)

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Uncomfortable Truths

- sensors are colour blind
- Bayer sensors do not generate full RGB

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United States Patent

Bayer

[11] **3,971,065**

[45] **July 20, 1976**

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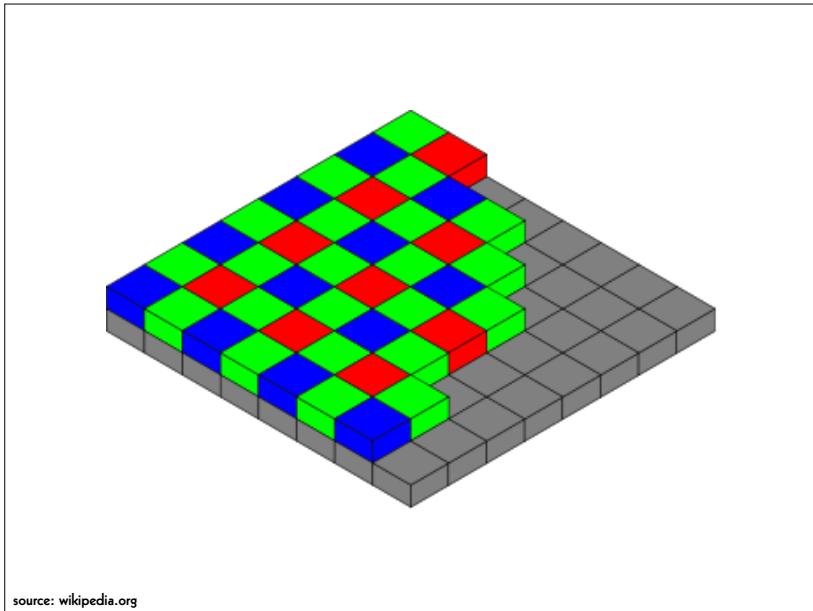
[56] References Cited UNITED STATES PATENTS

2,446,791	8/1948	Schroeder.....	358/44
2,508,267	5/1950	Kasperowicz.....	358/44
2,884,483	4/1959	Ehrenhaft et al.	358/44
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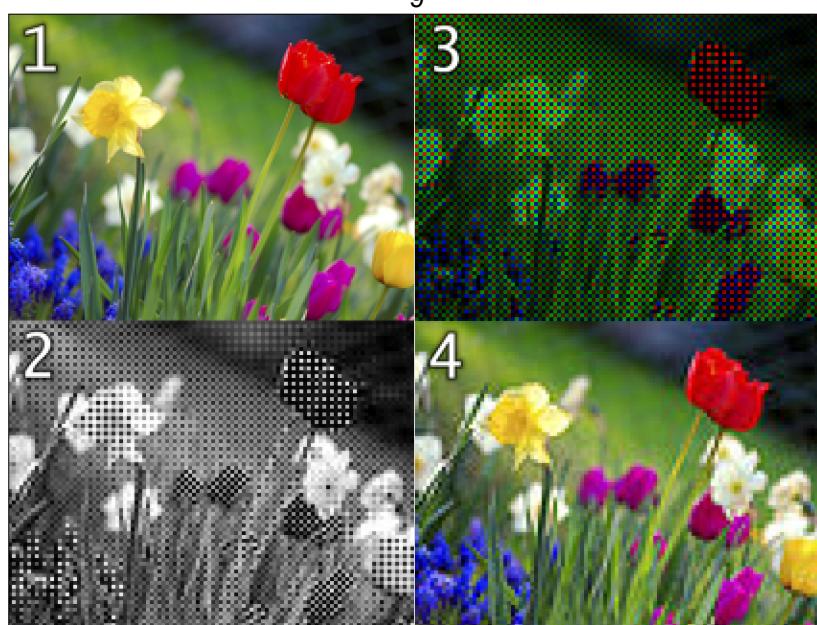
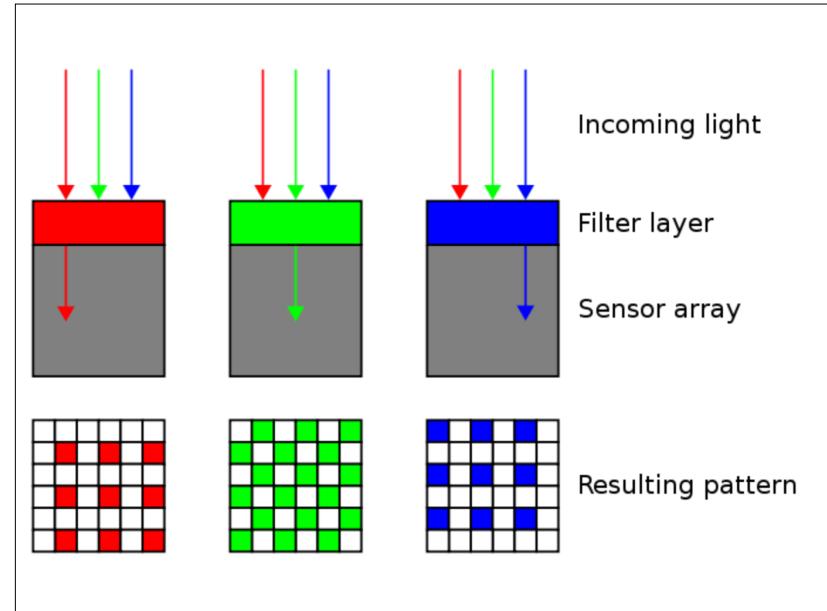
Primary Examiner—George H. Libman
 Attorney, Agent, or Firm—George E. Grosser

11 Claims, 10 Drawing Figures

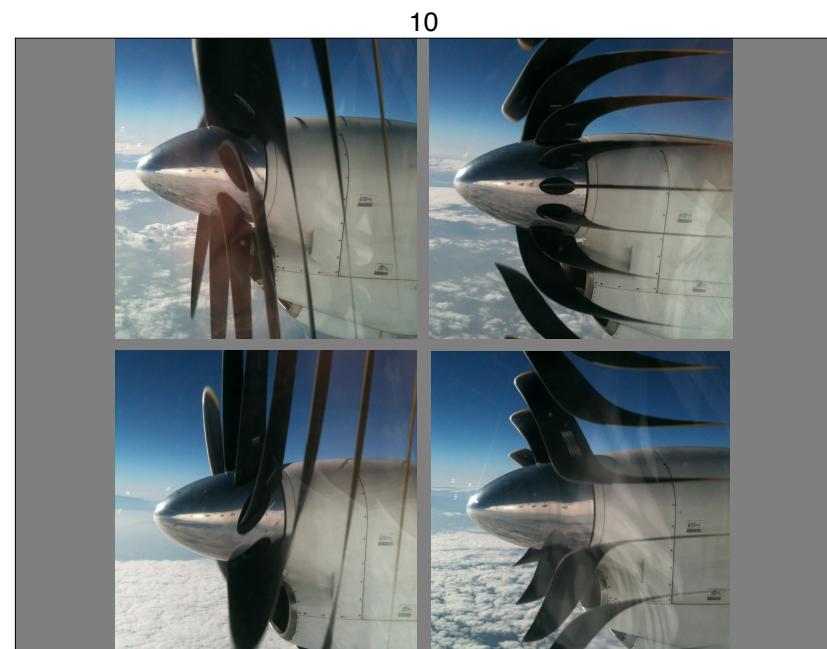
8



source: wikipedia.org



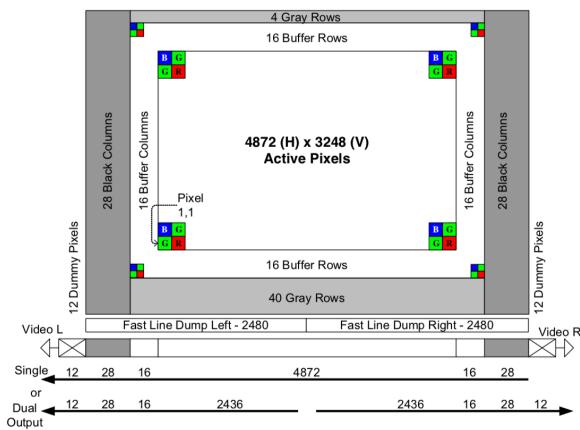
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DEVICE DESCRIPTION

ARCHITECTURE



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LINE TIMING CONTINUOUS MODE

Line Timing Single Output

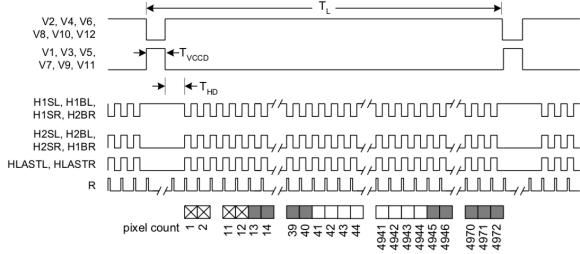
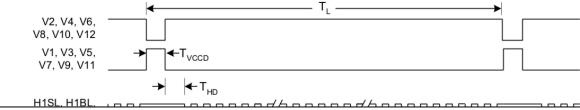


Figure 10: Line Timing Single Output

Line Timing Double Output



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COLOR WITH MICROLENS QUANTUM EFFICIENCY

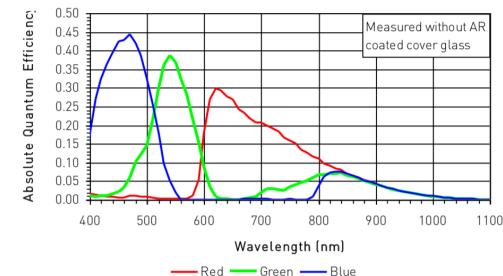


Figure 5: Color with Microlens Quantum Efficiency

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Fast Dump Gate Trailing Delay	T_{FDT}	0.5			μs
VCCD Line Clock Leading Edge Delay	T_{VL}	0.2	0.3		μs
VCCD Line Clock Trailing Edge Delay	T_{VT}	0.0	0.2	0.4	μs

MAIN TIMING - CONTINUOUS MODE

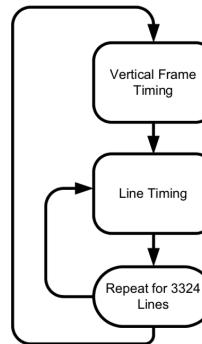


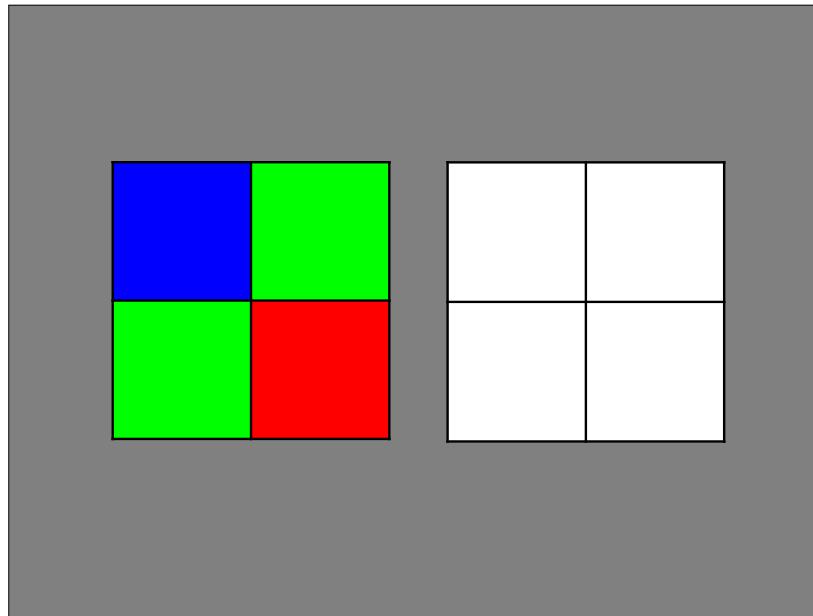
Figure 8: Main Timing - Continuous Mode

16

0111010100101010100010110101011110
0100110101010101010100001011101010
0111010100101010100010110101011110
0001**110101010101010100001011101010**
0110101001010101010001011010101111
0010101010101010000101110101010000
0111010100101010101000010111010101110
01010101010101000010111010100110
1001011101010010101010001011010101
11100101010101010000101110101010
01110101001010100010110101011110
01010101010101001101010100000001
0010100010101010100101010101010101

Present

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0111010100101010100010110101011110
0100110101010101010100001011101010
0111010100101010100010110101011110
0001110101010101010100001011101010
0110101010101010101010001011101010
0110101010101010101010001011101010
0010101010101010000101110101010000
011101010010101010000101110101010000
011101010010101010000101110101010000
0101010101010101000010111010100110
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0111010100101010100010110101011110
0101010101010101001101010100000001
0010100010101010100101010101010101

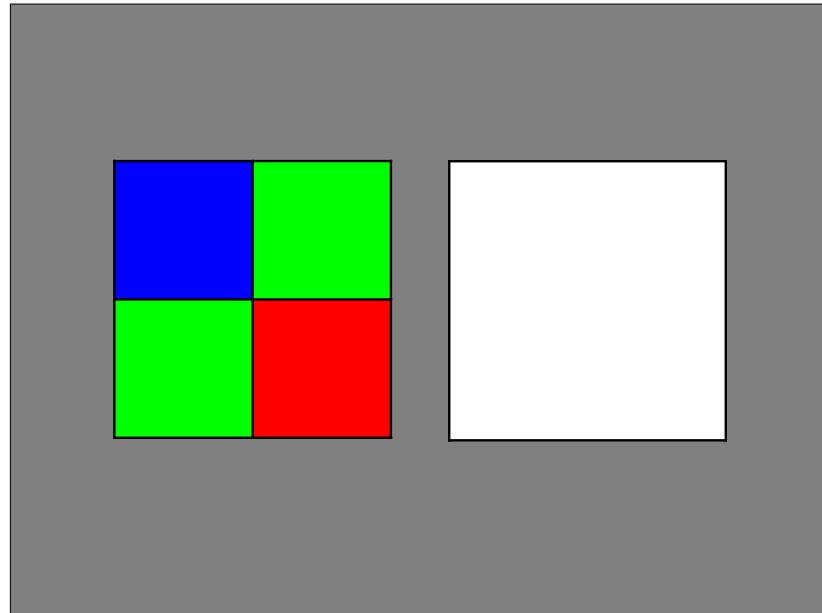
18

000000000000 000000000000 110101010101	000000000000 000000000000 010100001011	010010100101 101101000001 110101010101	011111011110 010100001011 100001100100
000000000000 101010011010 000000000000	000000000000 101001010101 000000000000	011000111001 101010011010 100001010111	010011011110 101001010101 010100010111

20

0 0 B	0 G₁ 0
0 G₂ 0	R 0 0

21

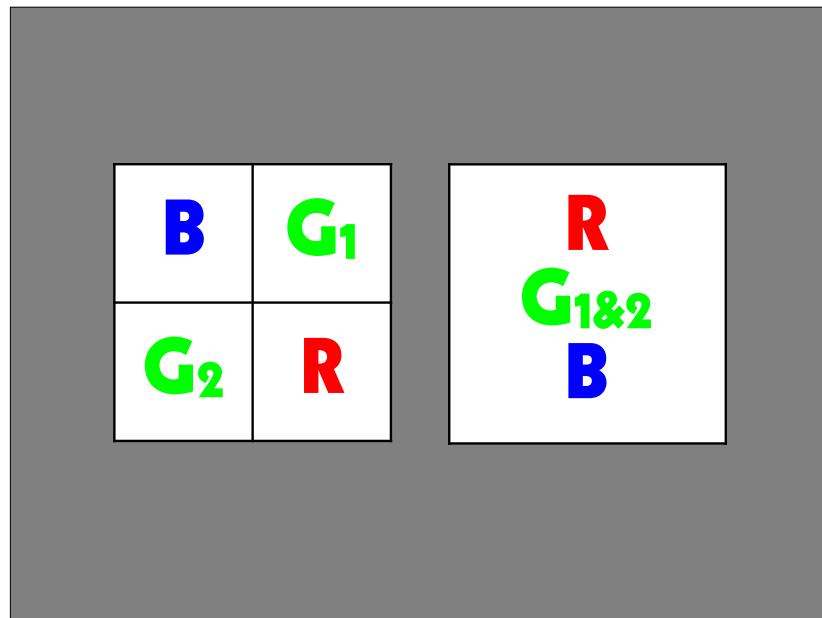


22

110101 010101	010100 001011
101010 011010	101001 010101

101001010101
011111010010
110101010101

23



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Two ways to use Bayer data

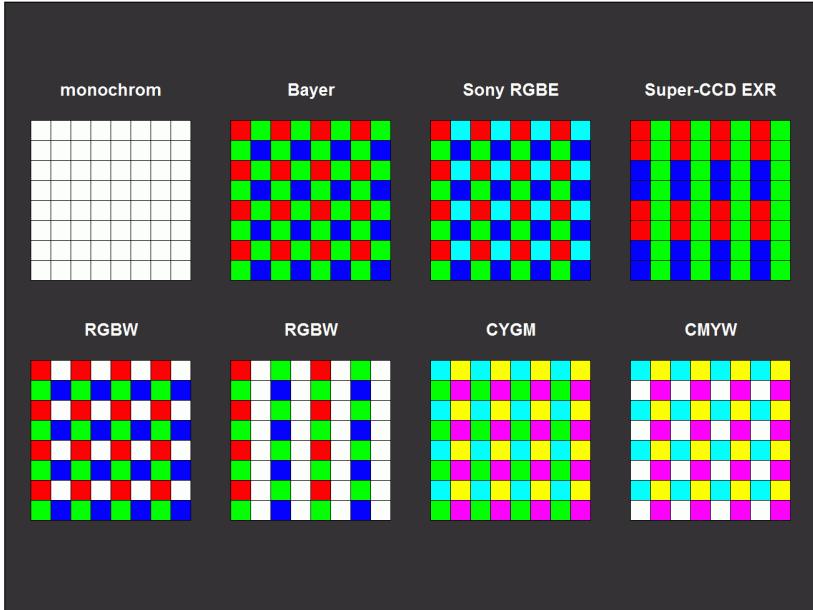
digital blow-up to RGB

- 3 times the amount of the generated data
- the file has the full sensor resolution
- only $\frac{1}{3}$ of the data are real

digital reduction to RGB

- $\frac{3}{4}$ the amount of the generated data
- the file has $\frac{1}{2}$ of the sensor resolution
- all data are real

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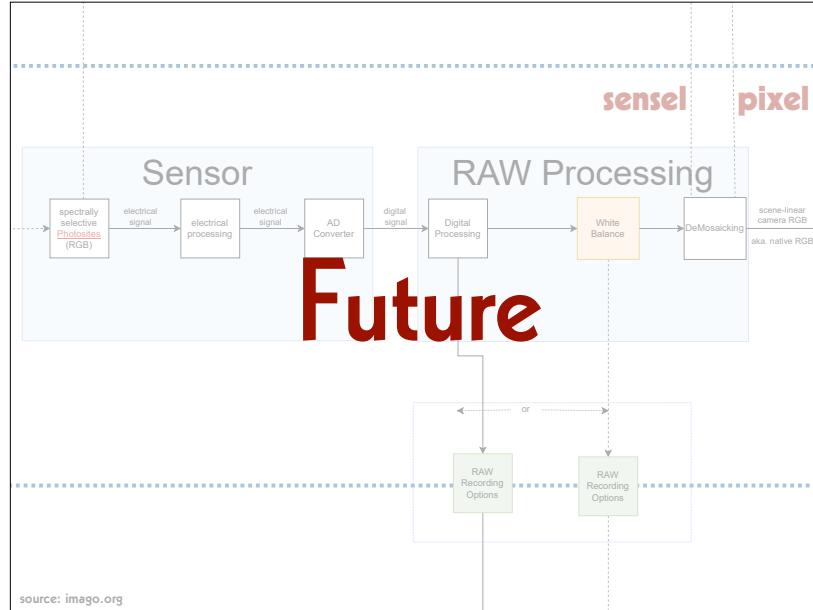
```
--demosaic=(BLI|BCI|LR|VNG|SI|PG|AMZE|HOLI|AHD|DLMMSEE)
demosaic a Bayer-encoded input_file into an RGB output_file

This option allows to choose between different demosaicing
algorithms, because the results may vary a lot, depending on the
image content.

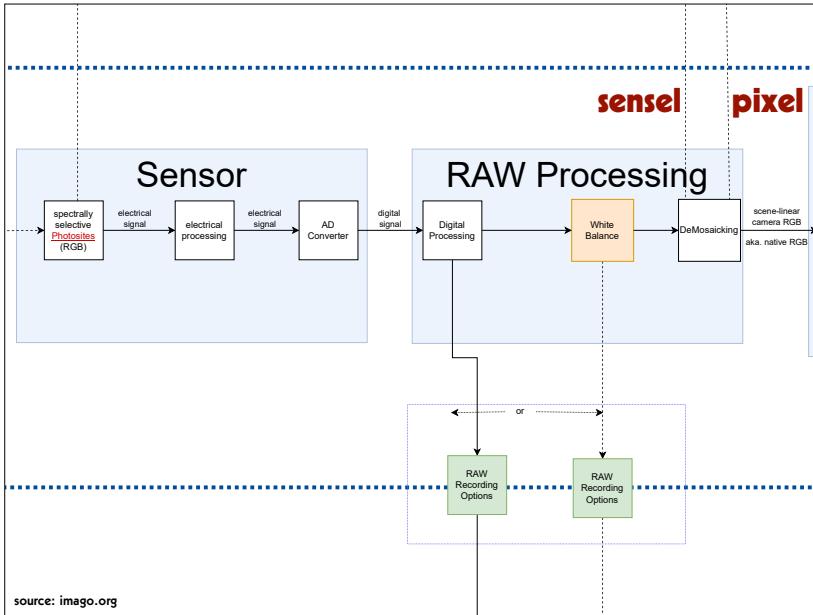
The following algorithms are implemented:
- BLI = bilinear interpolation
- BCI = bicubic interpolation
- LR = Lanczos resampling
- VNG = variable number of gradients
- SI = spline interpolation
- PG = pixel grouping
- AMZE = aliasing minimisation and zipper elimination
- HOLI = high-quality linear interpolation (Malvar, He and Cutler.
IEEE 2004)
- AHD = adaptive homogeneity-directed (Hirakawa and Parks. IEEE
2005)
- DLMMSEE = directional linear minimum mean square-error estimation
(Zhang and Xiaolin. IEEE 2005)

INFORMATIVE OPTIONS
-h, --help
```

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FFV1: Directions (1)

- support of the Y'C_GC_G colour model
- support of Bayer-type data
- support of any channel
- support of 1D and 3D LUTs
- support of HDR

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Stream: Internet Engineering Task Force (IETF)
RFC: 9043
Category: Informational
Published: August 2021
ISSN: 2070-1721
Authors: M. Niedermayer D. Rice J. Martinez

RFC 9043 FFV1 Video Coding Format Versions 0, 1, and 3

Abstract

This document defines FFV1, a lossless, intra-frame video encoding format. FFV1 is designed to efficiently compress video data in a variety of pixel formats. Compared to uncompressed video, FFV1 offers storage compression, frame fixity, and self-description, which makes FFV1 useful as a preservation or intermediate video format.

Status of This Memo

This document is not an Internet Standards Track specification; it is published for informational purposes.

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FFV1: Directions (2)

- revision of the bit stream
- tuning of the compression algorithm (speed and rate)

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[WIP] Multispectral support #138

Michael Niedermayer committed on 10 Jan 2019

commit 90f98045d4b0771d800c6bc62b97d1b5067ce5e7

```

@@ -731,10 +731,32 @@ Parameters( ) {
731   colorspace_type           | ur
732   if (version >= 1)          |
733   bits_per_raw_sample       | ur
734 -  chroma_planes           | br
735 -  log2_h_chroma_subsample | ur
736 -  log2_v_chroma_subsample | ur
737 -  extra_plane              | br
734 +  if (colorspace_type < 2) {
735 +    chroma_planes           | br
736 +    log2_h_chroma_subsample | ur
737 +    log2_v_chroma_subsample | ur
738 +    extra_plane              | br
739 +  } else {
740 +    plane_count              | ur
741 +    per_plane_metadata_count | ur
742 +    for( i = 0; i < plane_count; i++ ) {
743 +      plane_type               | ur
744 +      center_frequency         | ur
745 +      frequency_response( center_frequency ) | ur
746 +      color_transfer_characteristic | ur

```

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until 31st January 2023

[WIP] Multispectral support #138

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commit 90f98045d4b0771d800c6bc62b97d1b5067ce5e7

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736 +    log2_h_chroma_subsample | ur
737 +    log2_v_chroma_subsample | ur
738 +    extra_plane              | br
739 +  } else {
740 +    plane_count              | ur
741 +    per_plane_metadata_count | ur
742 +    for( i = 0; i < plane_count; i++ ) {
743 +      plane_type               | ur
744 +      center_frequency         | ur
745 +      frequency_response( center_frequency ) | ur
746 +      color_transfer_characteristic | ur
893
894 +  ### plane_type
895 +
896 +  `plane_type` indicates the semantic type of the plane.
897 +
898 +  | value | plane_type
899 +  |-----|:
900 +  | 0 | Unspecified
901 +  | 1 | Emissive
902 +  | 2 | Absorptive
903 +  | 3 | Reflective
904 +  | 4 | Retro-Reflective
905 +  | 5 | Mask
906 +  | 6 | Depth
907 +  | 7 | Motion
908 +  | 8 | Error
909 +  | 9 | Force Field
910 +  | 10 | Polarization
911 +  | 11-999 | Reserved
912 +
913 +  ### per_plane_metadata_count
914 +
915 +  `per_plane_metadata_count` allows future extension of the information we store about planes
916 +

```

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from 1st March 2023

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